

Armature Reaction Field Adjustment in Permanent Magnet Synchronous Generators

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Permanent Magnet Synchronous Generator

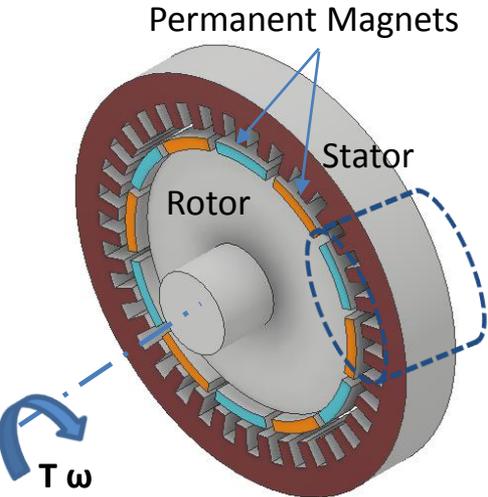


Fig: PMSG

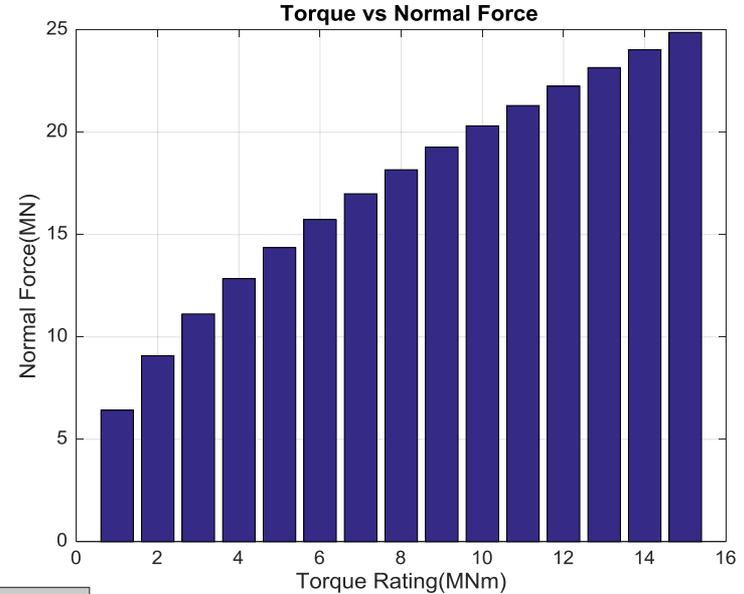
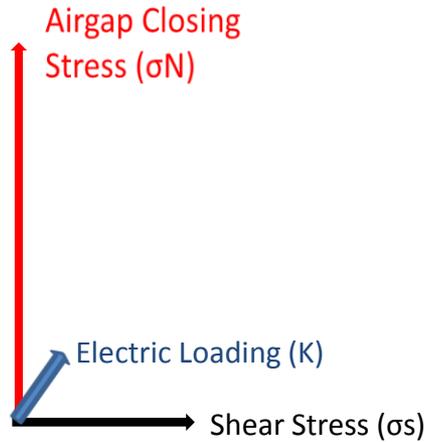


Fig: Normal Force Scaling

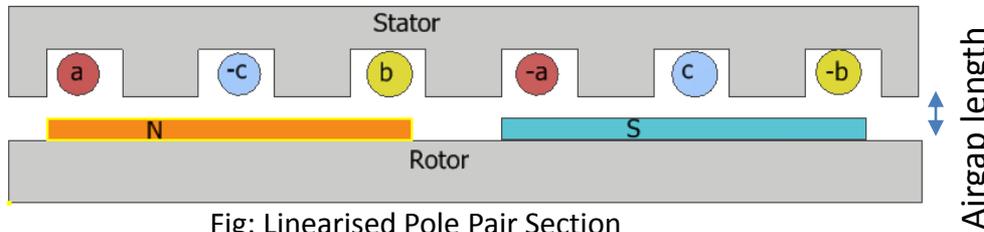
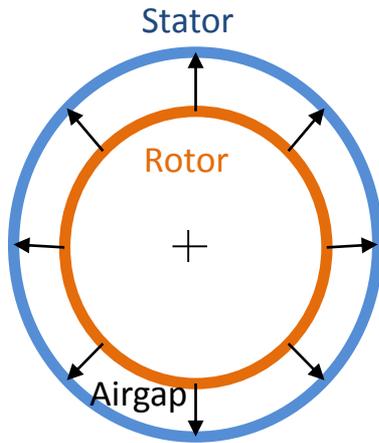


Fig: Linearised Pole Pair Section

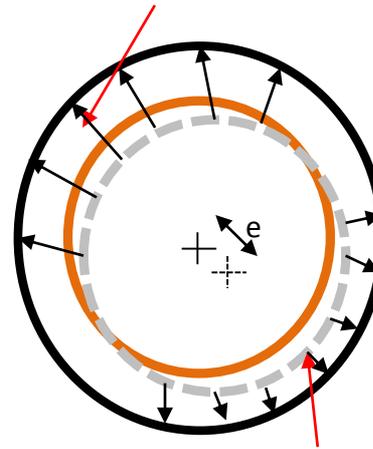
Problem (Unbalance Magnetic Pull)



Uniform Airgap Length and Uniform forces

Fig: Ideal Case

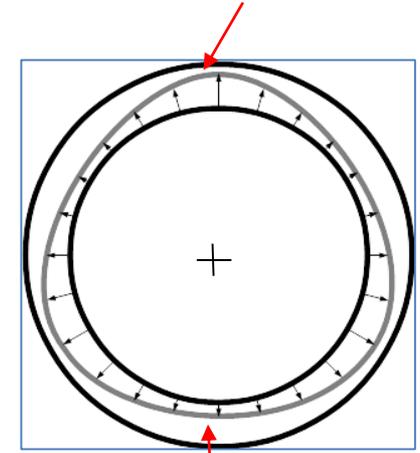
Large airgap region/ Small Force



Small airgap region/ Large Force

Fig: Due to Eccentricity

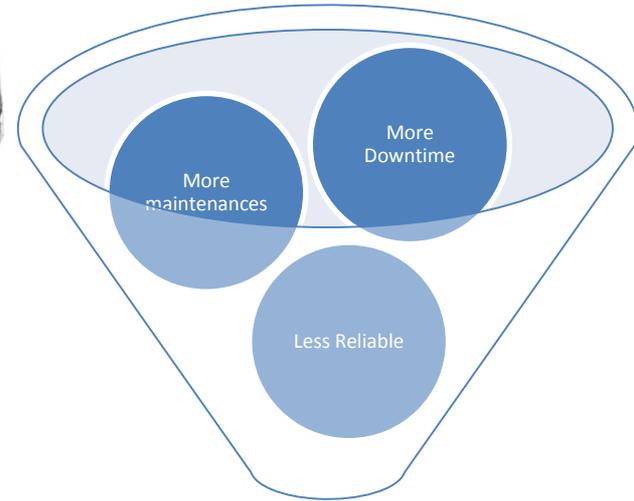
Small airgap region/ Large Force



Large airgap region/ Small Force

Fig: Due to Shape Deformation

Consequences (Unbalance Magnetic Pull)



Unbalance Magnetic Pull

Bearing wears

Excessive Vibration

Additional Loss

Airgap Collapse

Loss of Revenue

Armature Field Adjustment

An electromagnetic approach to uniformize airgap forces.

- What?

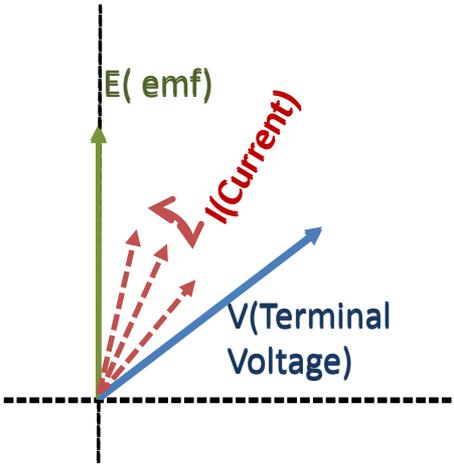


Fig: Phasor Diagram

- What is achieved?

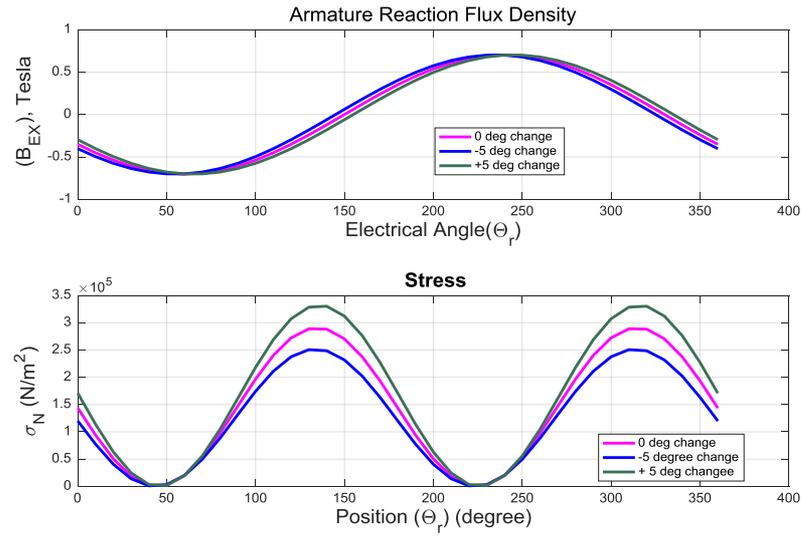
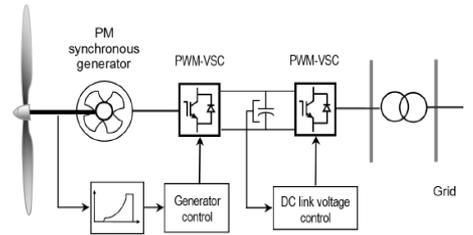


Fig: Airgap Closing Stress in a pole pair section

- How?



- Pulse width modulation of PEC
- We don't bother about power factor at generator side.

Implementation (A Concept of Modular Stator)



Fig: Siemens new Modular Generators [1]

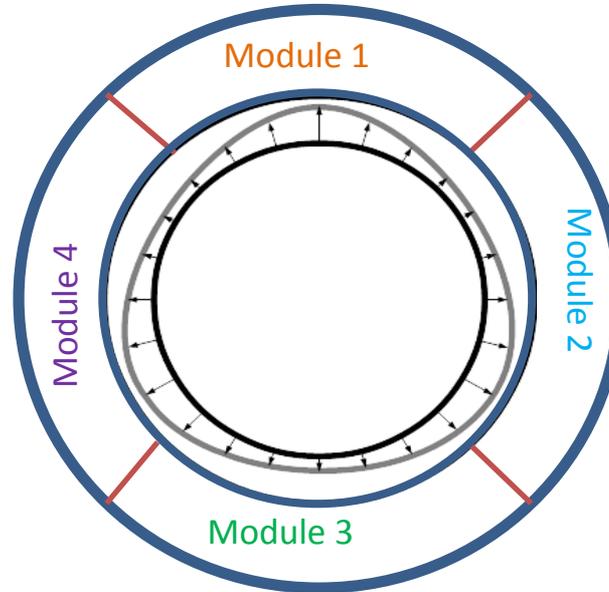


Fig: Single Rotor but many modules of stator.

Approximate Linear
Modules in stator

Each Sections will be
symmetrical and
balanced 3 phase

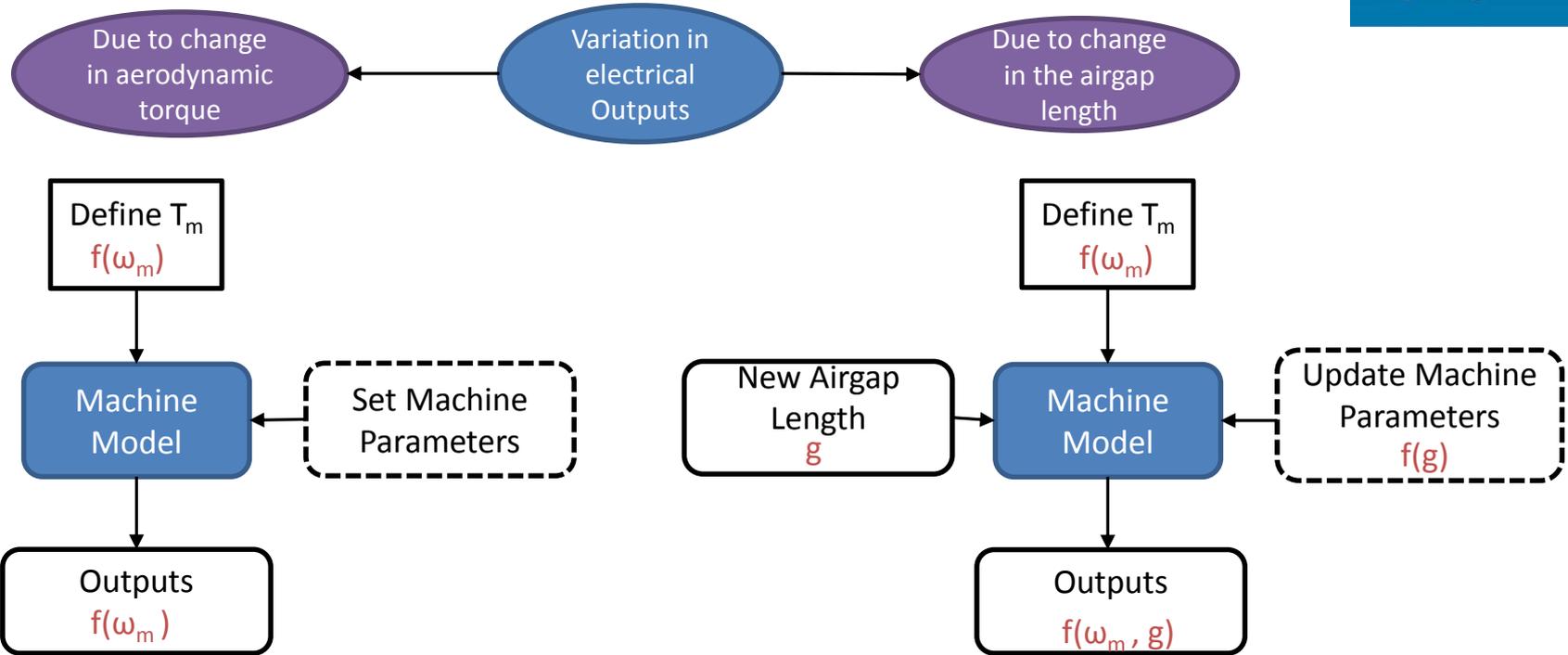
AR can be adjusted
independently

Over all can address
higher modes of airgap
defromation

[1]<https://www.siemens.com/press/en/pressrelease/?press=/en/pressrelease/2012/industry/drive-technologies/idt2012094045.htm>

Estimation of Airgap length for each Modules

(A Sensorless approach)



Currents, Voltages and Speed

Fig: Fixed Airgap Model

Currents, Voltages and Speed

Fig: Updated Model - Variable airgap

Airgap estimation

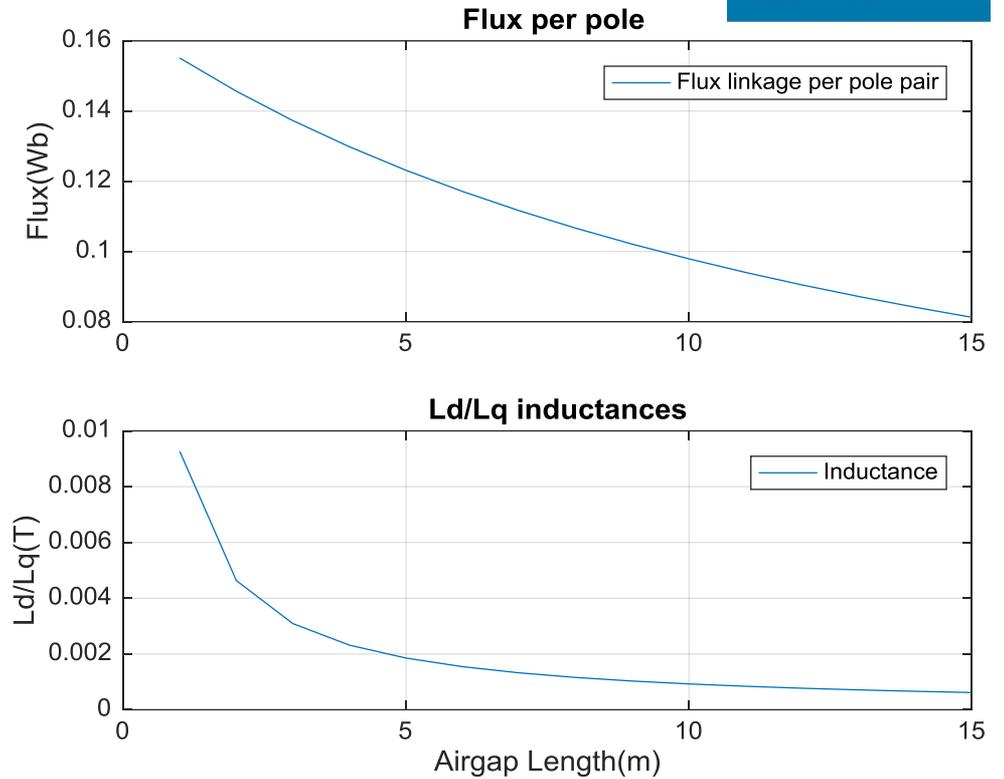
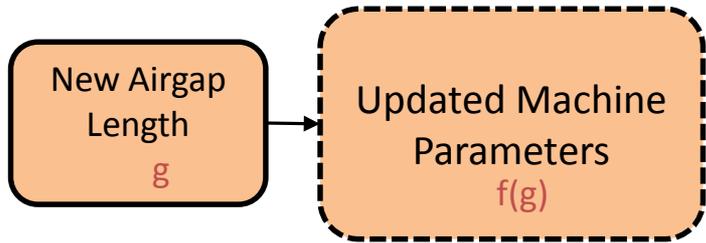
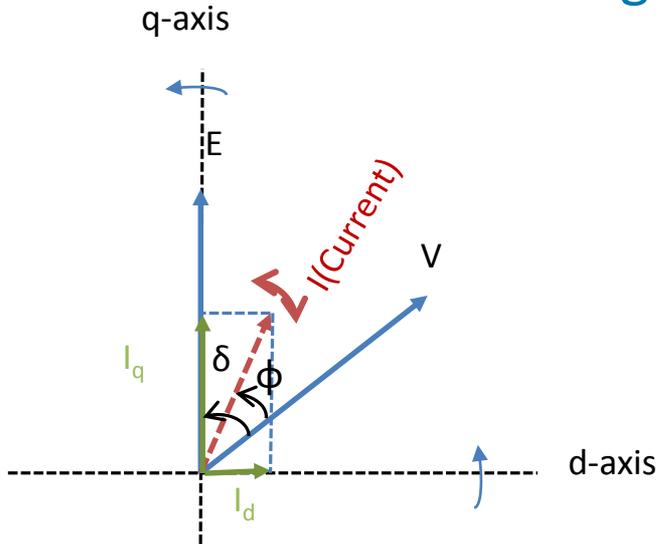


Fig: Correlation between airgap length and machine parameters

Airgap Estimator



D-Q Components of currents

I_q : Torque producing component

I_d : Flux controlling component

I_q and I_d determines phase angle

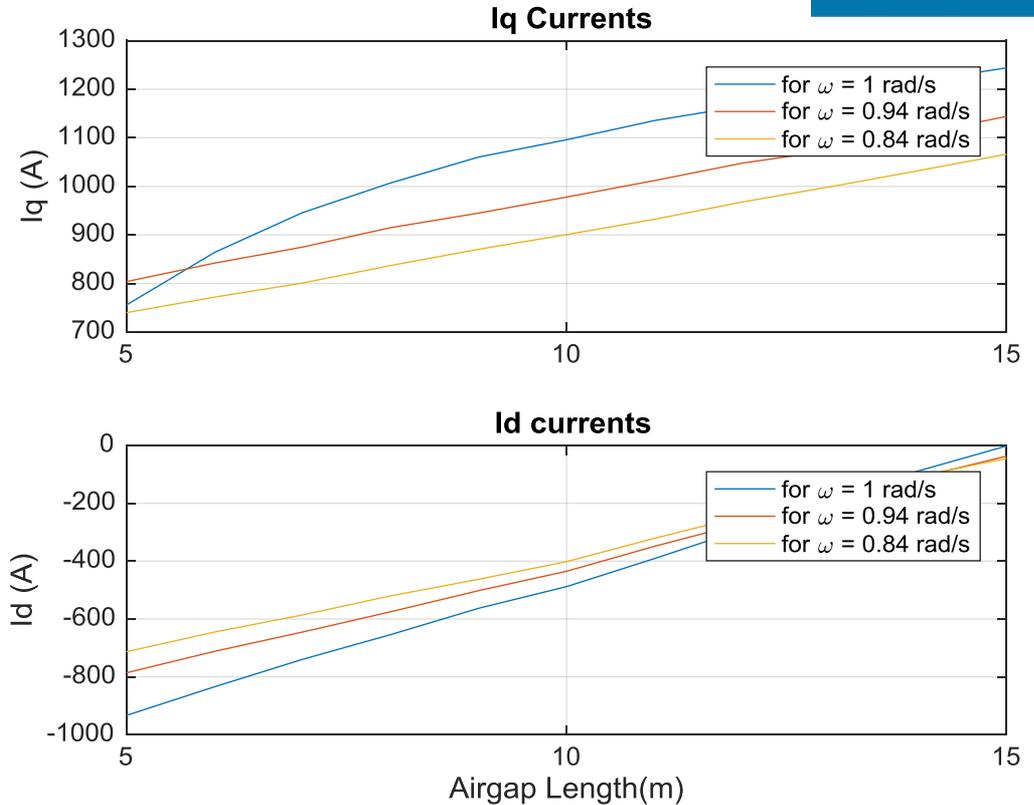


Fig: Correlation between airgap length and Current outputs

Experimental Model

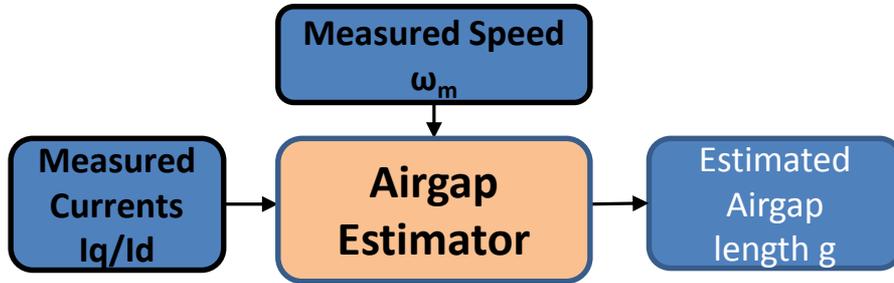


Fig: Airgap Estimator.

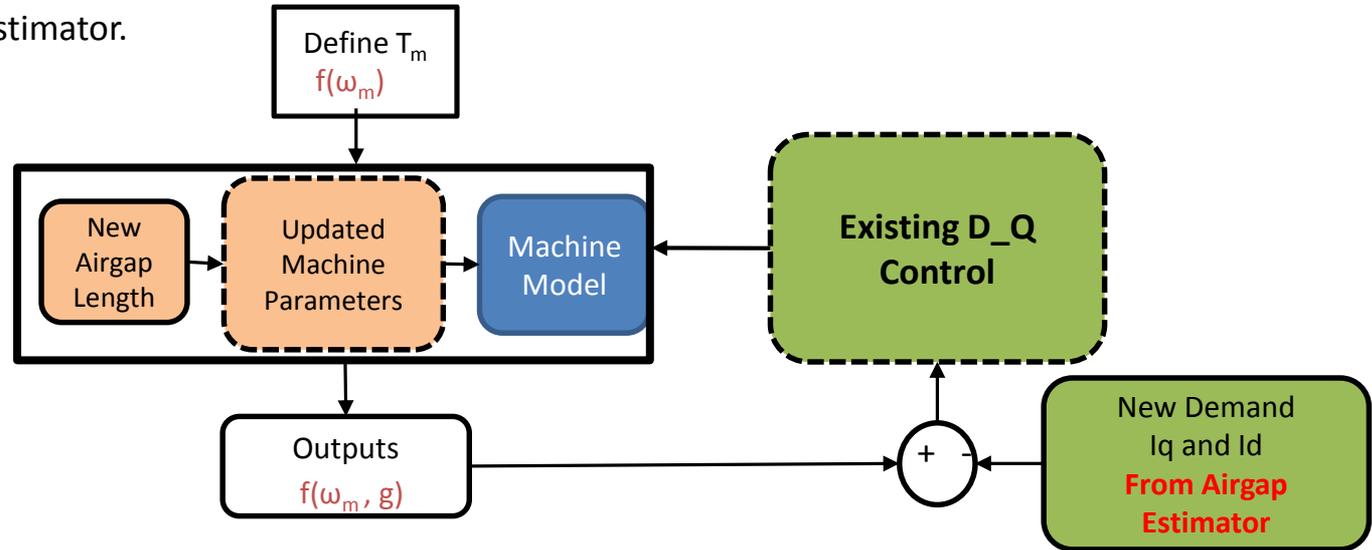


Fig: Control logic for correcting airgap length deviation.

Significance

Less Mass and Saving in Capital cost

- Uses inherent machine's field to create magnetic bearing effects.
- No additional electromagnetic materials
- Introduces room for having less stiff materials.
- Sensorless approach to detect airgap length

Simplicity

- Make use of existing control System

Updated Information

- Up to date information on airgap length and its deformations

Saving in O&M Cost

- Early detection of airgap anomalies ease maintenance task.
- Knowledge of magnitude of unbalance magnetic pull informs operator for severe damage warnings.
- Once Co-ordinated with all the segments, magnetic field in the airgap can be balanced at all time.



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